

Model Checking Communicating Processes: Run Graphs, Graph Grammars & MSO

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Formal Methods & Verification group Brussels

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Agenda

- ⇒ formal model of distributed recursive communicating processes
- ⇒ recall un-/decidability of basic verification questions
- ⇒ show line of attack via under-approximative approaches

- ⇒ from semantic “boundedness” to graph grammars
- ⇒ and back to decidability of MSO model checking

article takes different way:

- ⇒ try to extend known results beyond reachability
- ⇒ directly arrive at undecidability
- ⇒ extend proof-idea of reachability result for subclass of RCPS
- ⇒ arrive at graph grammars for run graphs
- ⇒ apply known HRG-treewidth-MSO connection

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Verification of Distributed Systems

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# Simple Reverse Echo Server
import socket

def send_rev_log(conn,l):
    if not l:
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    else:
        conn.send(l[-1])
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HOST = ''
PORT = 54321
s = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
s.bind((HOST, PORT))
s.listen(1)

conn, addr = s.accept()

log=[] # local pushdown store

while 1:
    msg = conn.recv(1024)
    if not msg: break

    if msg.startswith("show"):
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        log.append(msg)
conn.close()
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from mpi4py import MPI

comm = MPI.COMM_WORLD
rank = comm.Get_rank()
assert comm.Get_size() == 7

if rank == 0: # process 0
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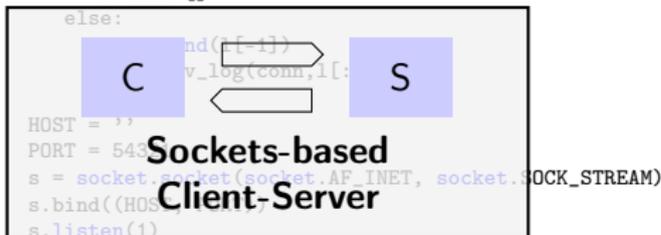
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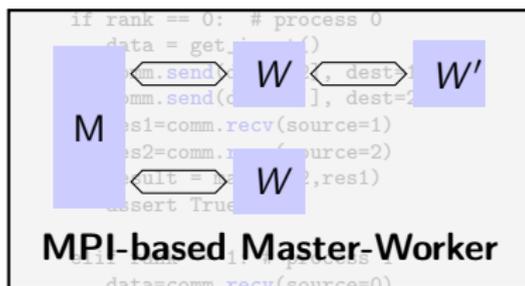
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check safety

Verification of Distributed Systems

check specification in formal logic

e.g., the server returns all received messages in reverse order

```
else:  
    conn.send(1[:-1])  
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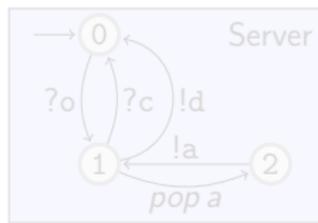
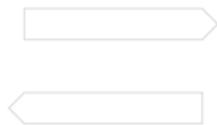
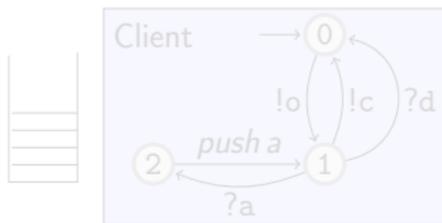
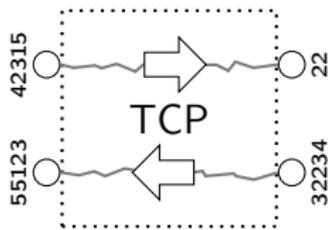
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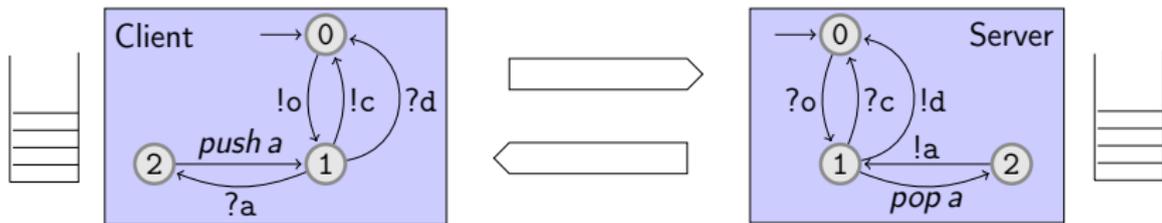
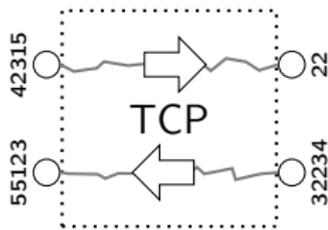
Formal Model : RCPS



Formalize by Recursive Communicating Processes

- reliable, asynchronous, unbounded channels \mapsto fifo queues
- network \mapsto (communication) graph / architecture
- recursion \mapsto pushdown stack

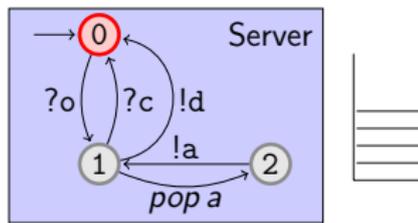
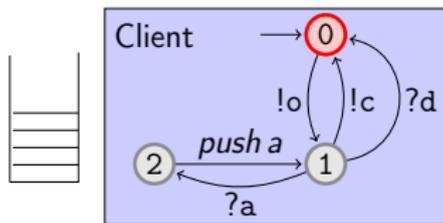
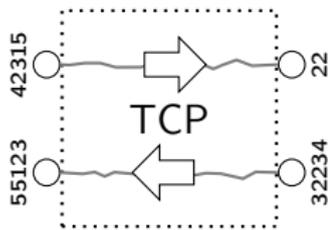
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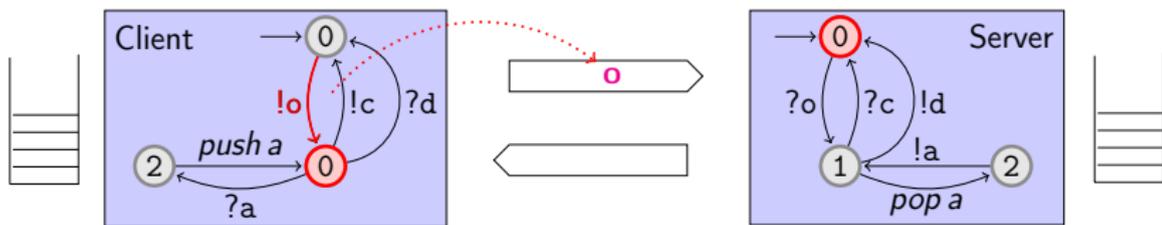
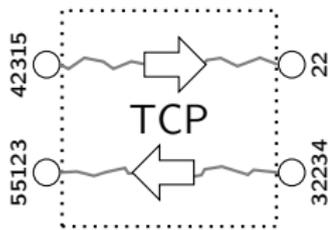
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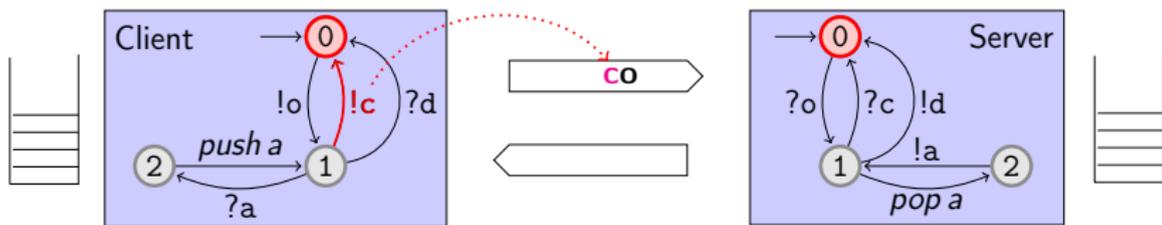
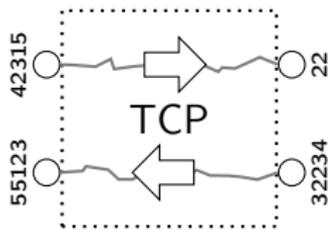
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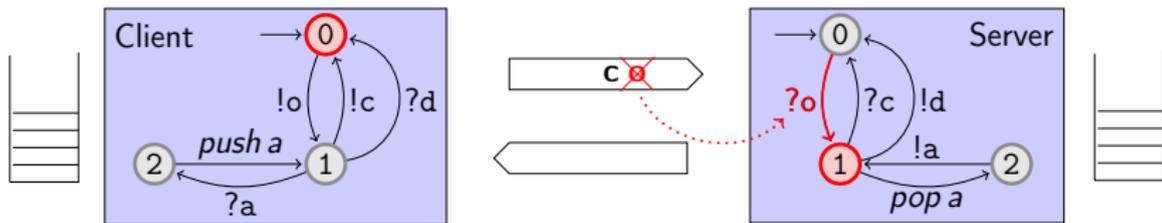
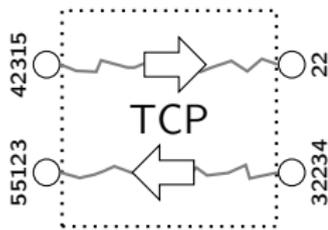
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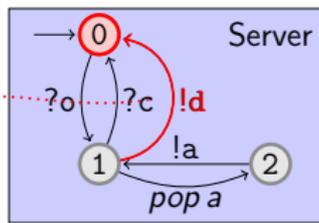
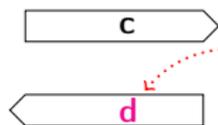
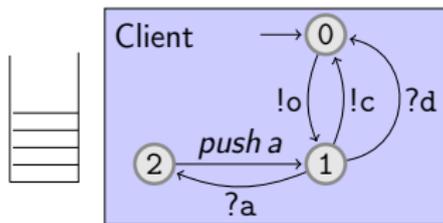
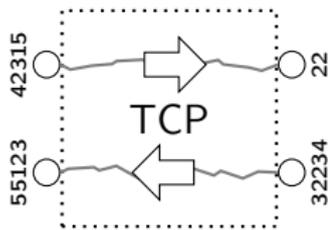
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Reachability Verification

⇒ reachability undecidable for finite-state RCPS ⚡

already  &  are Turing powerfull

↻ need to avoid cyclic communication: impractical 😞

⇒ and for simple non-cyclic architectures with pushdowns ⚡

already for   : PCP/intersect. of cf langs

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Idea:

Restrict focus only on subset of possible runs that have a certain form (under-approximate behaviour).

⇒ try to find restriction on runs that have

(i) good theoretical properties (decidable reachability etc.)

(ii) is "applicable" in practical domain

(iii) can decide (or approximate) if property holds

(iv) algorithm can be implemented

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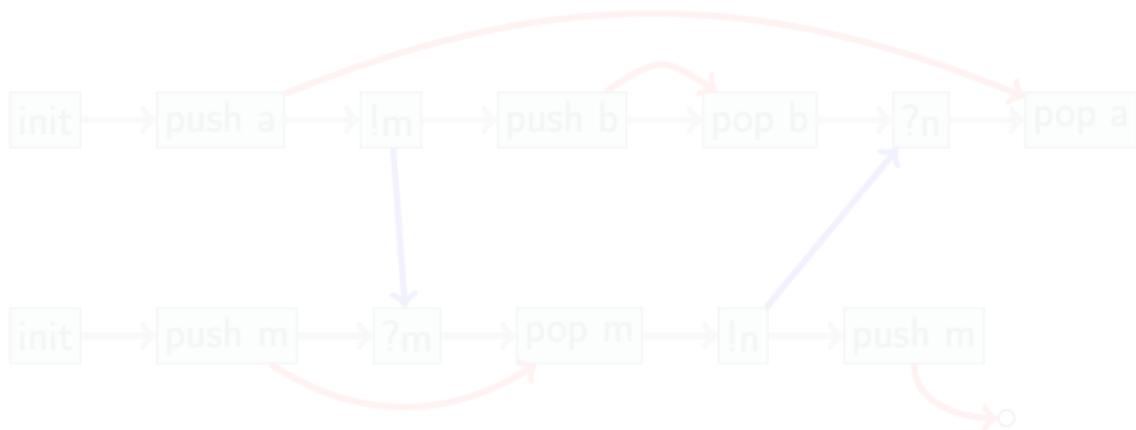
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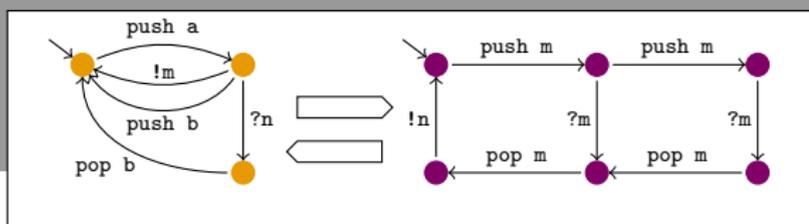
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⇒ event-based/partial-order semantics (run graph)



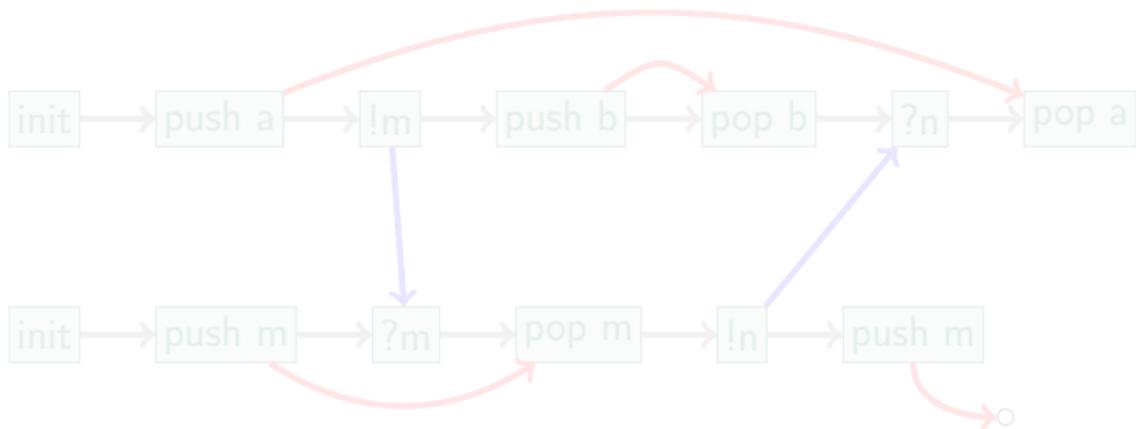
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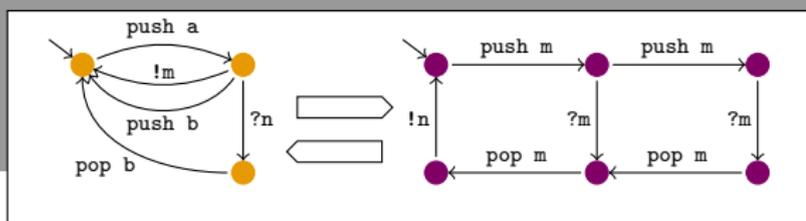
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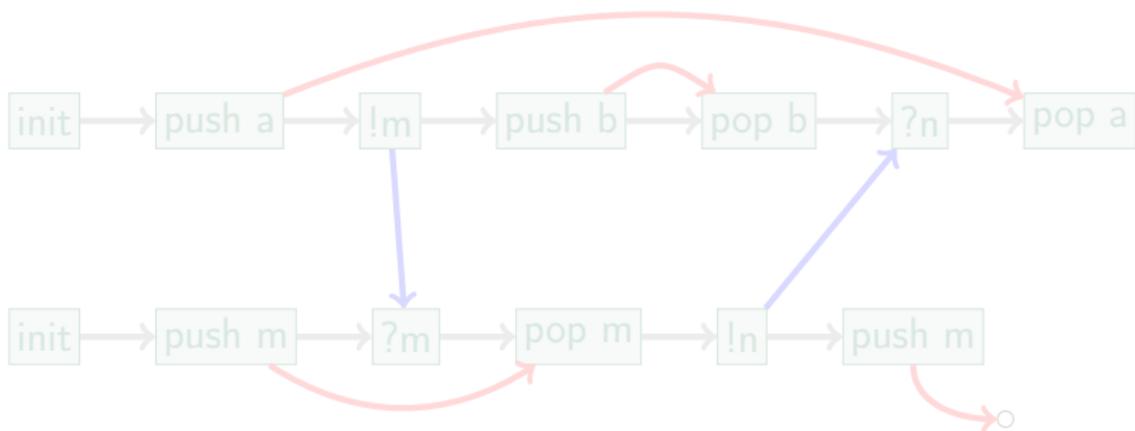
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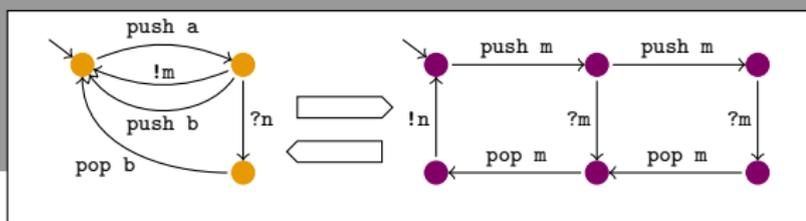
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$s_0, \text{push } a, s_2, !m, s_3, \text{push } b, s_4, \text{push } m, s_5, ?m, s_6, \text{pop } b, s_7, \dots$
 $\dots, s_7, \text{pop } m, s_8, !n, s_9, ?n, s_{10}, \text{push } m, s_{11}, \text{pop } a, s_{12}$

⇒ event-based/partial-order semantics (run graph)



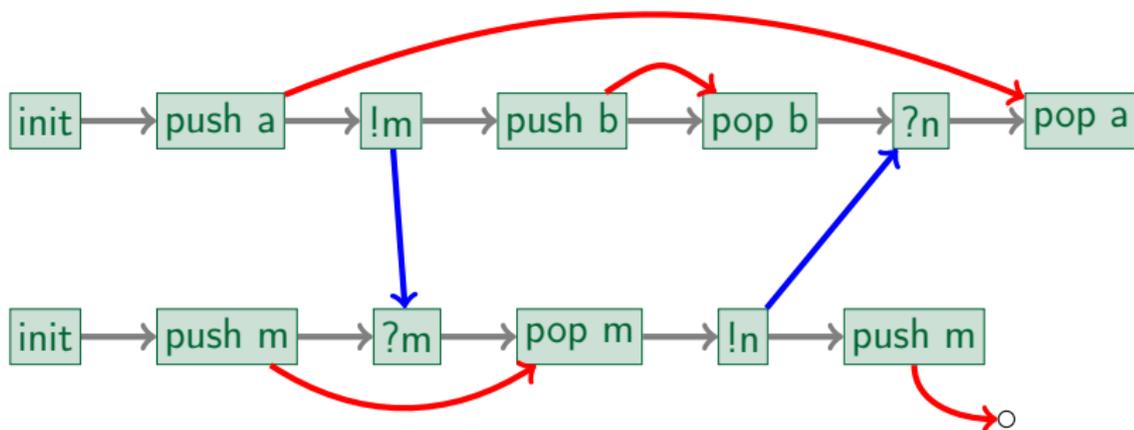
Runs of RCPS



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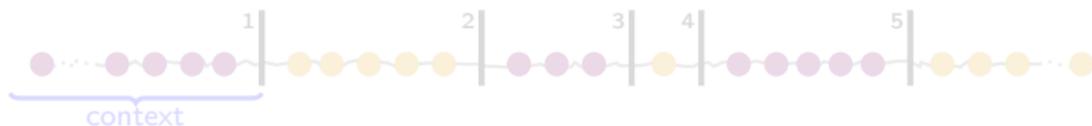


Boundedness Conditions: Interleaving

⇒ “resource”-boundedness

- atomic communication
- untangle pushdown and communication actions
- architecture: tree-like, acyclic, . . .
- mixed: half-duplex, . . .

⇒ family of phase-boundedness restrictions:
e.g., contexts [Qadeer/Rehof'05]

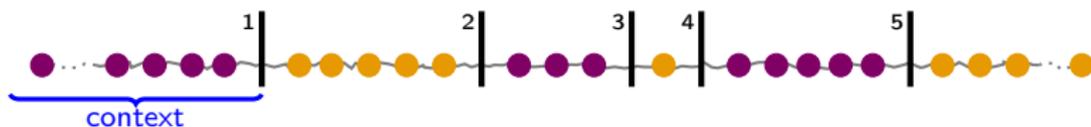


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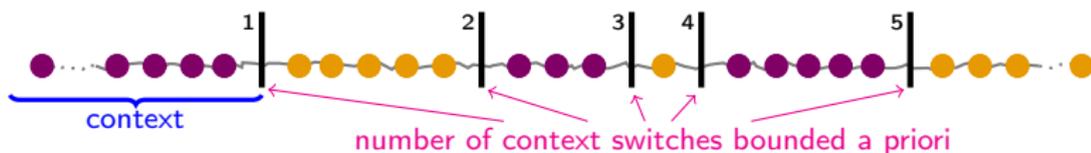
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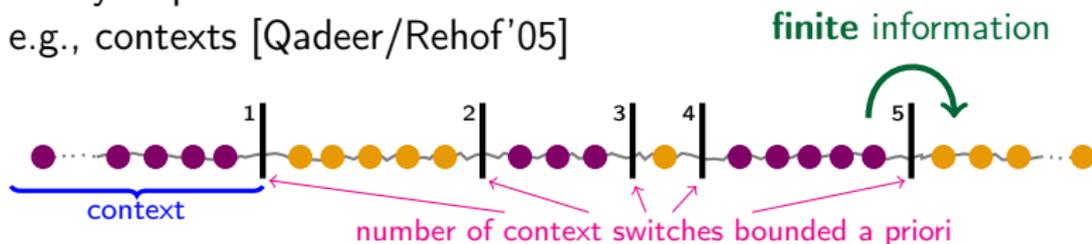
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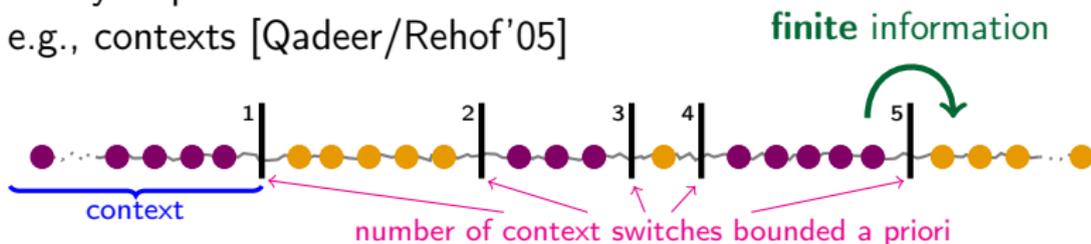
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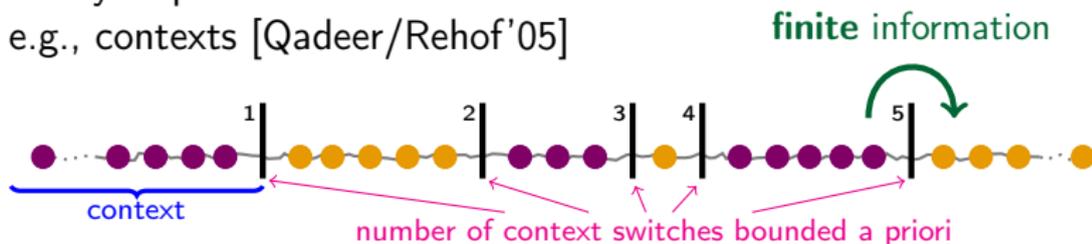
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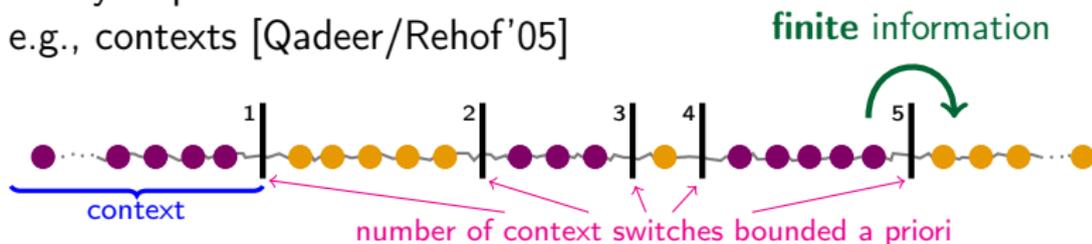
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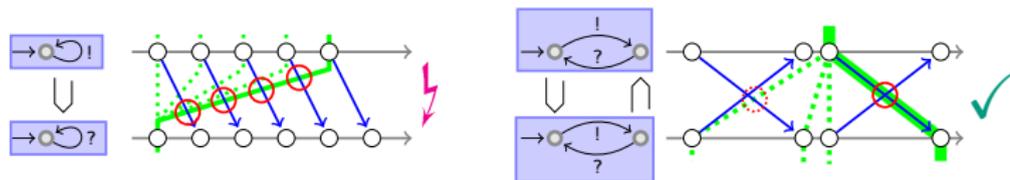
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Boundedness: Partial-Order Case

- ⇒ bounded MSC (= bounded finite-state RCPS)
 - fix size of channels a priori: finite system ✓
 - **semantically** fix channel usage:
for all prefixes of any run the number of unreceived messages on each channel is less than or equal to b
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 - allows to decompose MSC into “building blocks”
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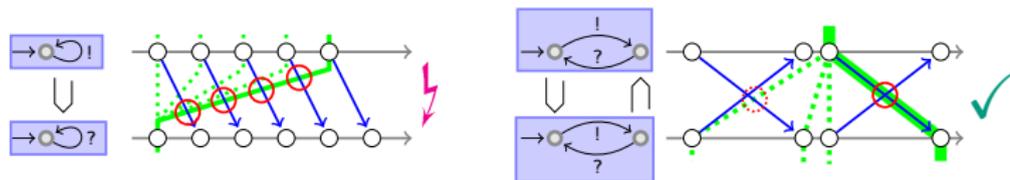
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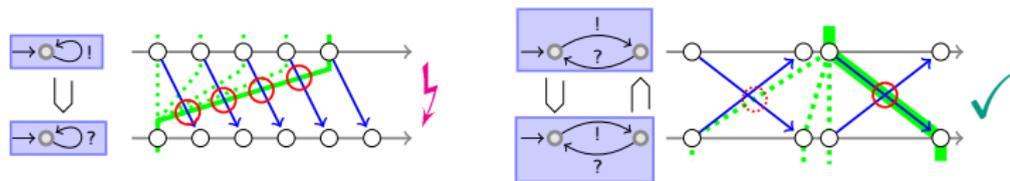
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How to extend MSO model checking ideas to RCPS ?



Derive more general notion of boundedness ?



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goal: proof one, get one for free !

Derive more general notion of boundedness ?

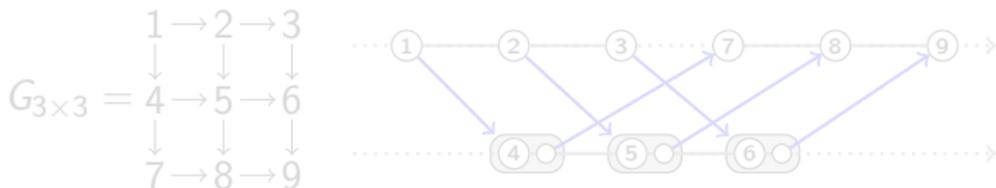


Again: Undecidability for finite RCPS

Theorem [Seese '75] :

Let \mathcal{C}_G be a class of graphs such that for every integer $k > 1$ there is a graph $G \in \mathcal{C}_G$ such that G has the $k \times k$ grid as induced subgraph¹. Then MSO is undecidable on \mathcal{C}_G .

⚡ MSO undecidable on rungraphs of finite-state RCPS as one can embed the $k \times k$ grid already on $p \leftrightarrow q$, e.g., for $k = 3$



• resembles Turing completeness proof [Brand/Zafiropulo '83]

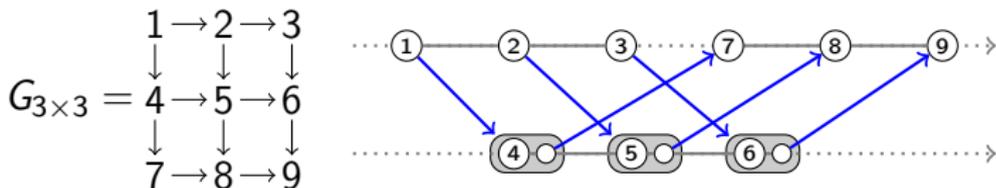
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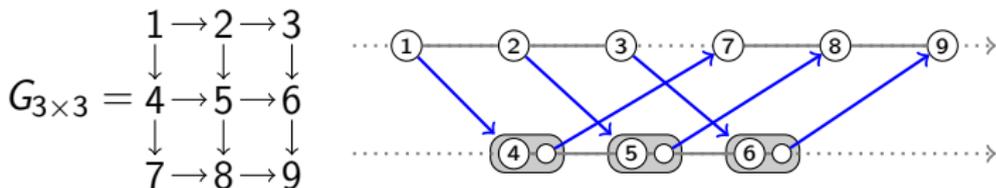
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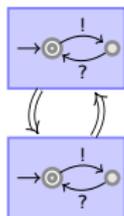
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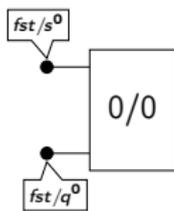
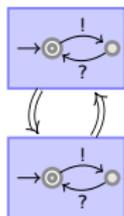
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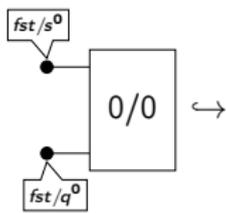
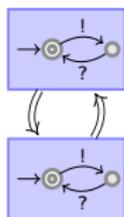
Rungraph of bounded finite-state RCPS



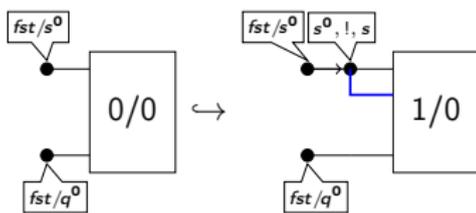
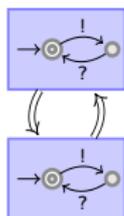
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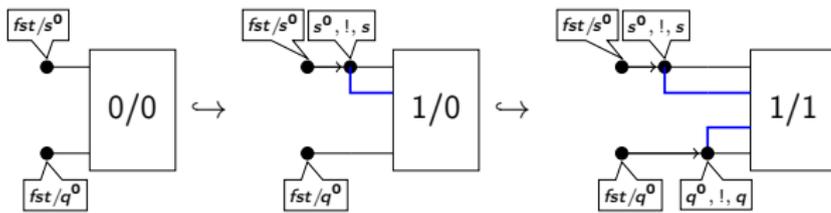
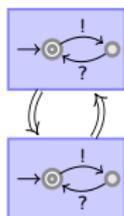
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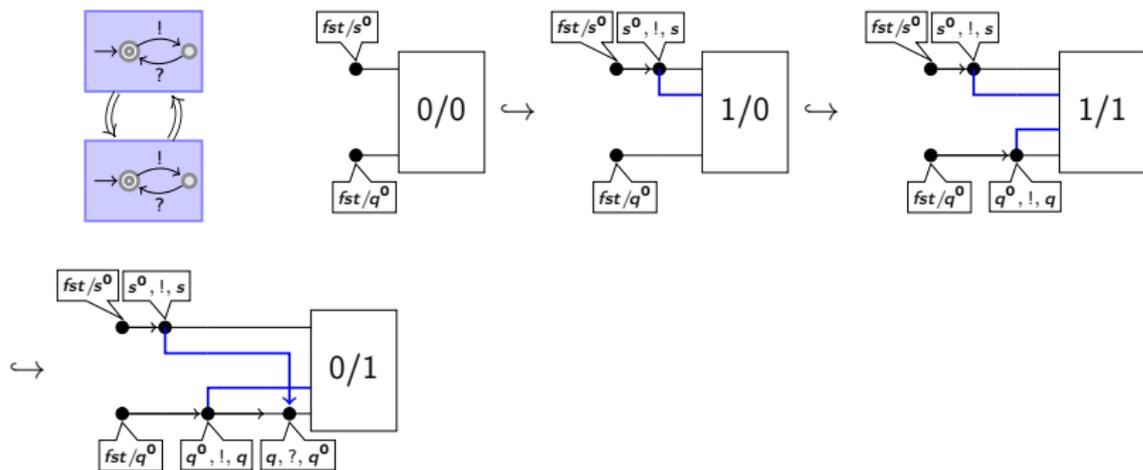
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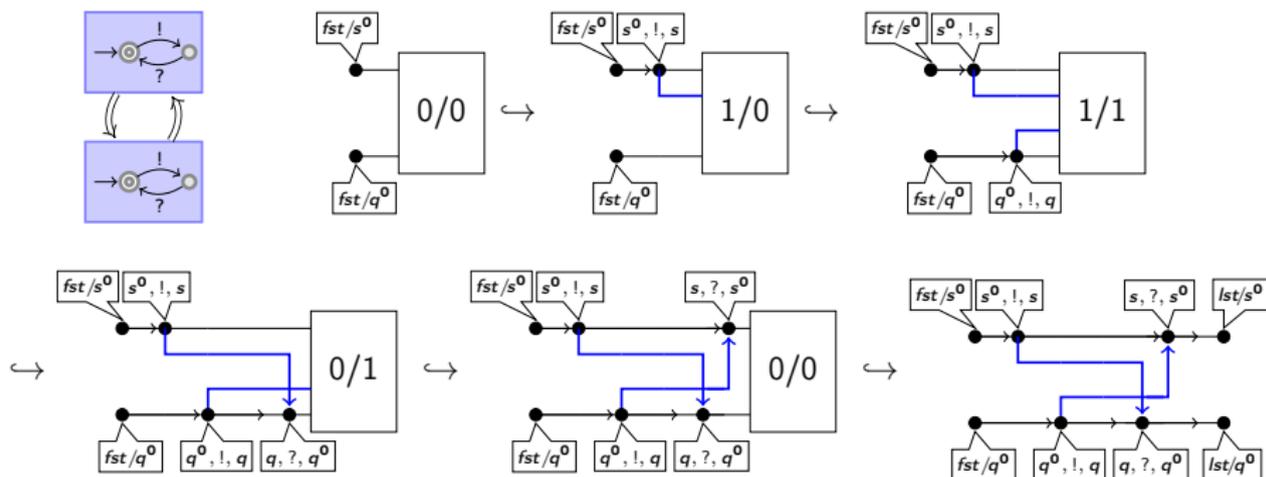
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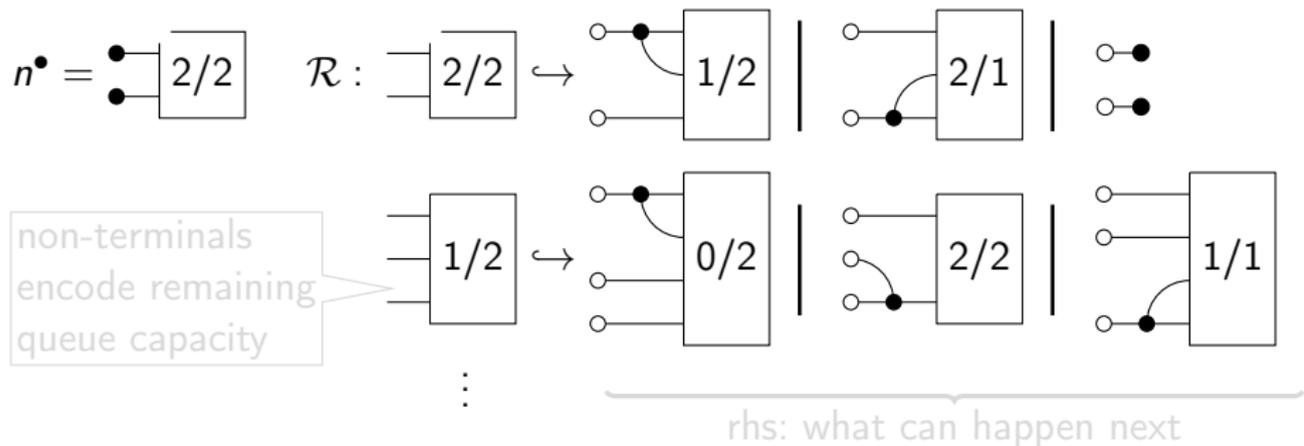
⇒ reminds of **derivations** of (context-free) graph grammars 😊

From HRG to MSO Decidability

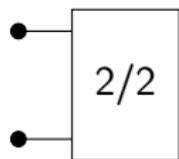
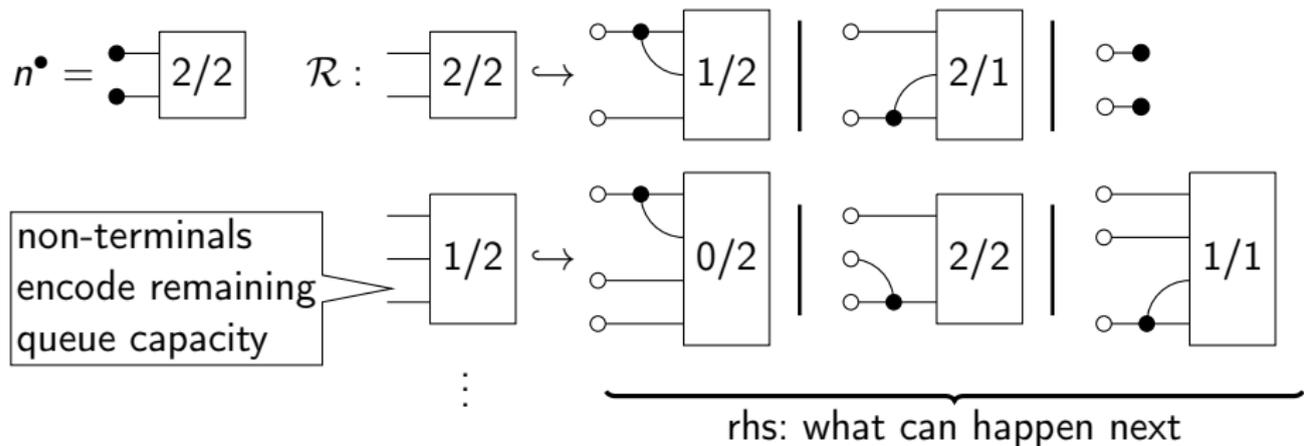
— **Theorem [Courcelle '12]** : —

Given an HRG that describes a class of graphs \mathcal{C}_G , and an MSO formula φ , then checking whether there exists a graph in \mathcal{C}_G that satisfies φ is decidable.

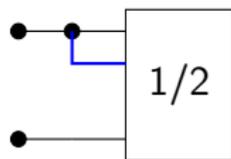
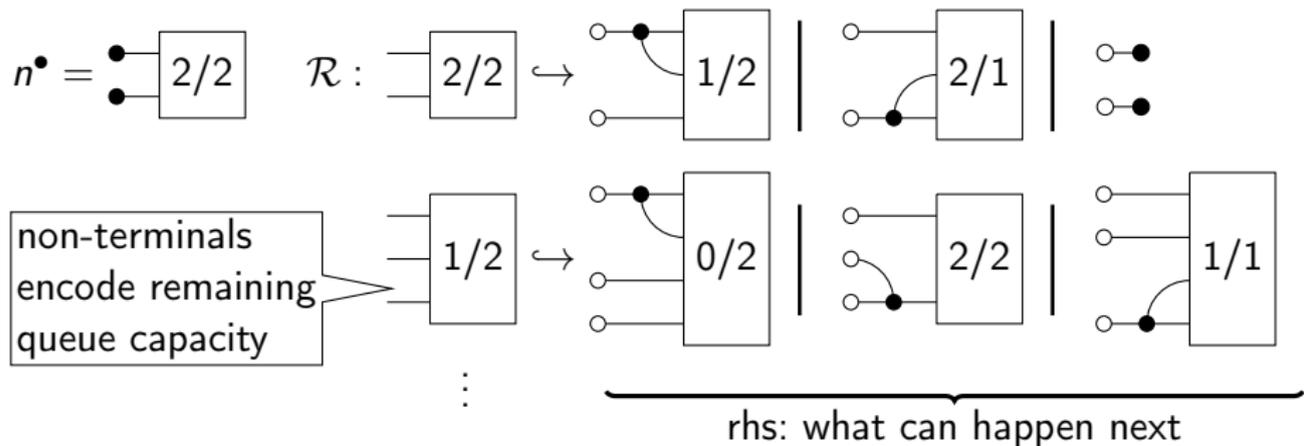
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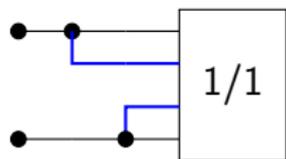
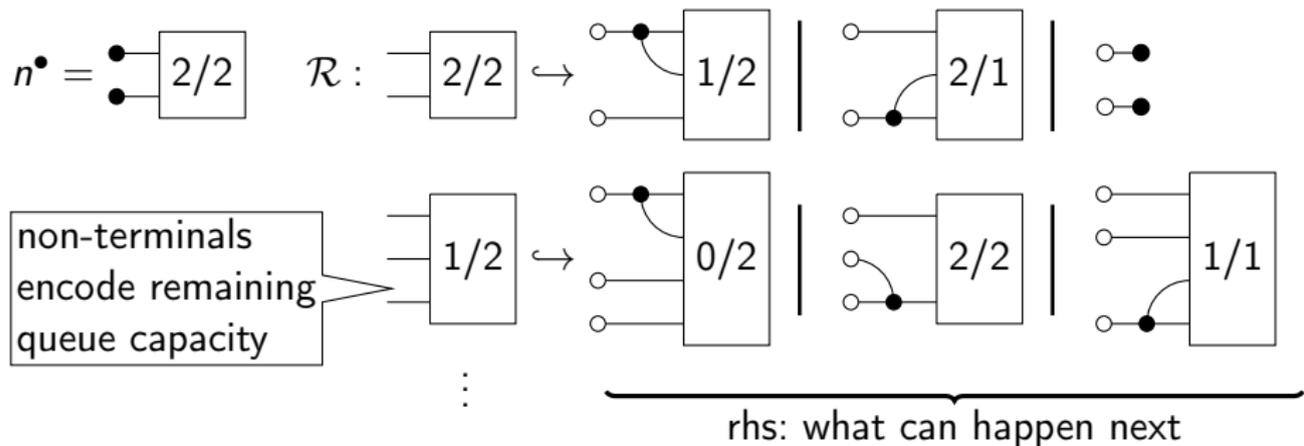
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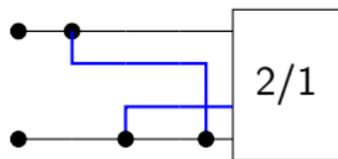
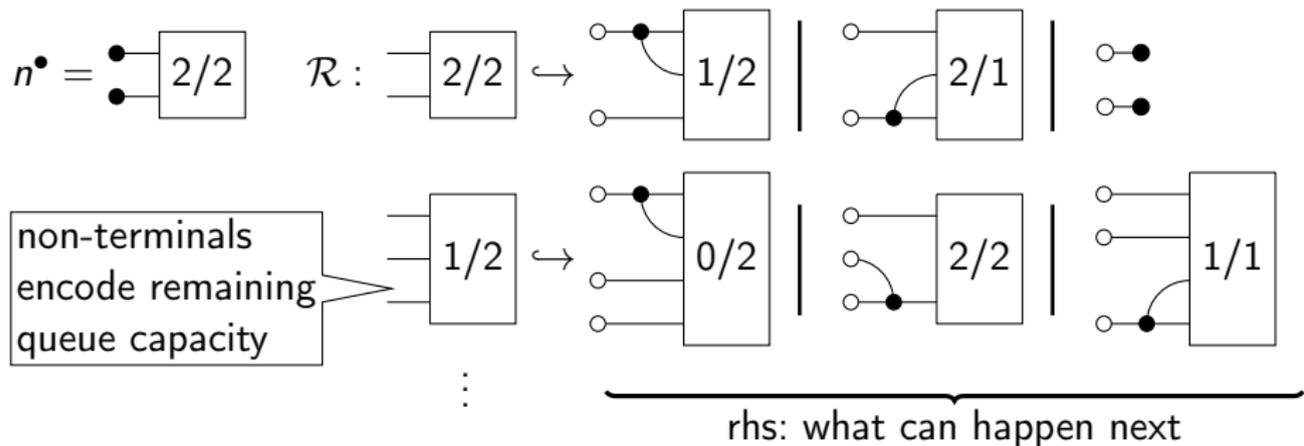
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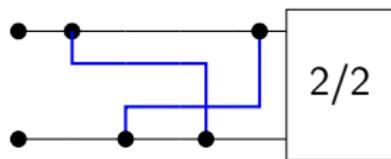
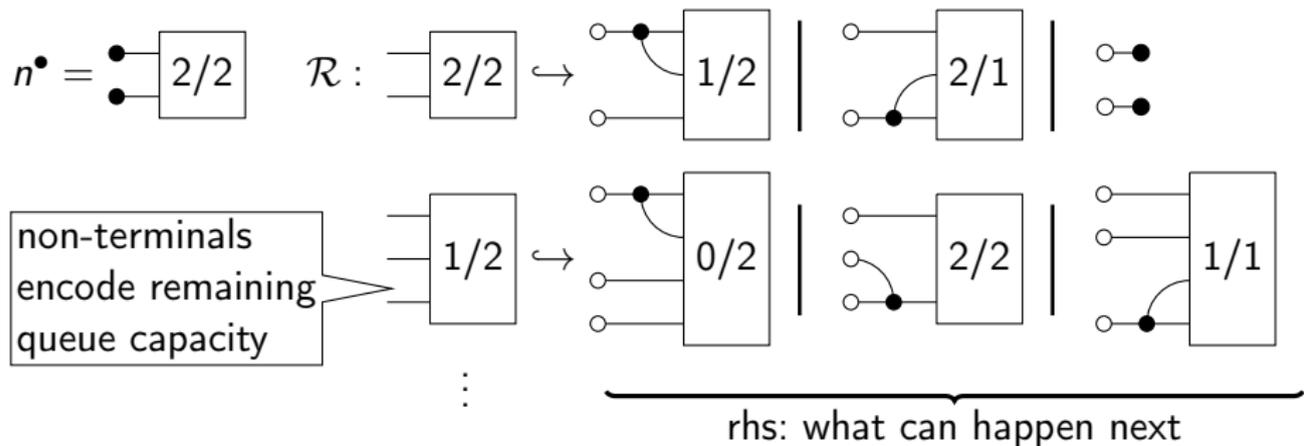
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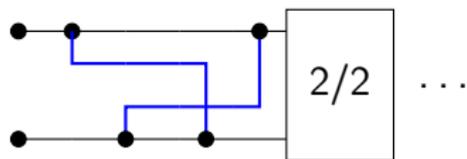
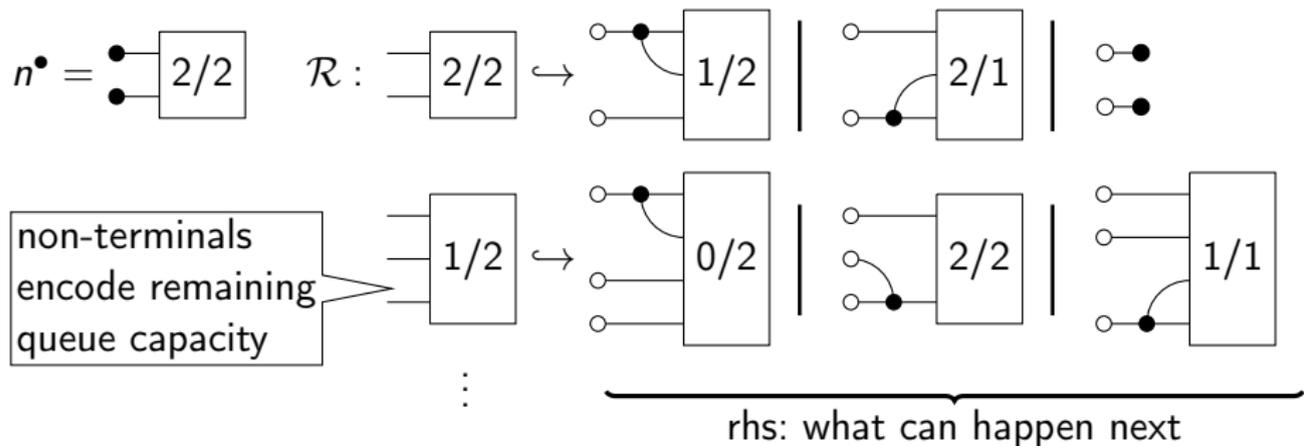
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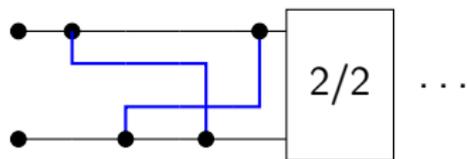
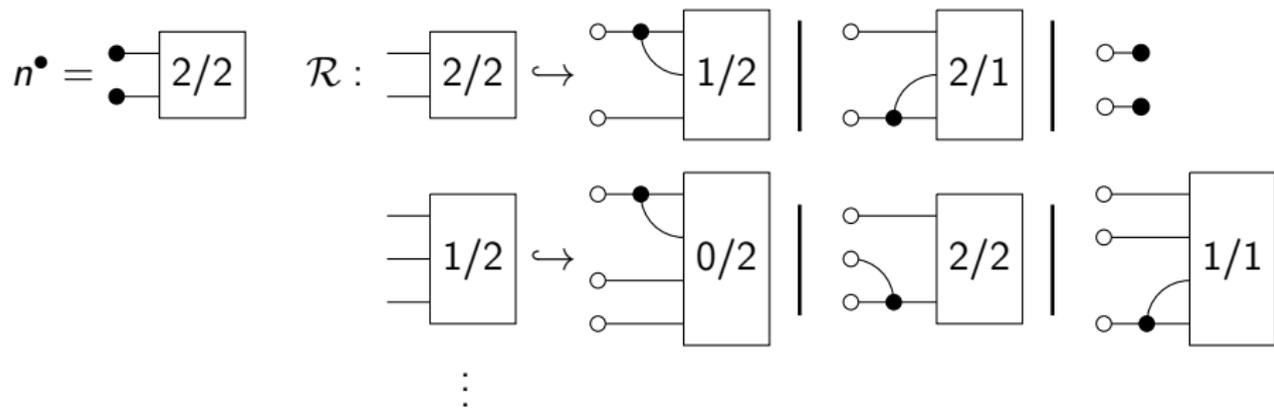
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A HRG for bounded finite RCPS



A HRG for bounded finite RCPS



- ⇔ HRG generates rungraphs of **2**-bounded finite RCPS of **2** processes
- ⇔ generalize: p processes and bound k
- ⇔ rulewidth of run graphs of bounded finite RCPS is in $\mathcal{O}(p \cdot k)$

From HRG to MSO Decidability

Proposition:

The MSO model checking problem is decidable for rungraphs of bounded finite-state RCPS.

⇒ already known [Madhusudan'03] [Genest et al.'07],
but here new “style” of proof 😊

⇒ by connection of HRG rulewidth with treewidth:

Corollary:

MSC of bounded finite-state RCPS have bounded treewidth.

⇒ bounded treewidth more general notion of semantic boundedness ?

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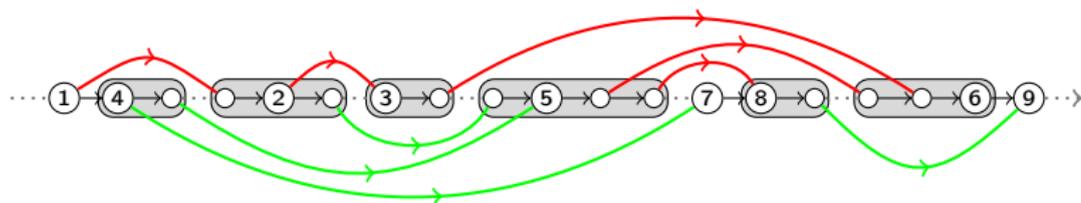
Undecidability for General RCPS

⇒ reachability (and MSO) undecidable for RCPS ⚡

idea: **infinite-grid-as-minor** argument !

- look at 2PDS (can reduce RCPS to this case)

$$G_{3 \times 3} = \begin{array}{ccccc} & 1 & \rightarrow & 2 & \rightarrow & 3 \\ & \downarrow & & \downarrow & & \downarrow \\ & 4 & \rightarrow & 5 & \rightarrow & 6 \\ & \downarrow & & \downarrow & & \downarrow \\ & 7 & \rightarrow & 8 & \rightarrow & 9 \end{array}$$



Ressource Bound \mapsto Grammar Bound

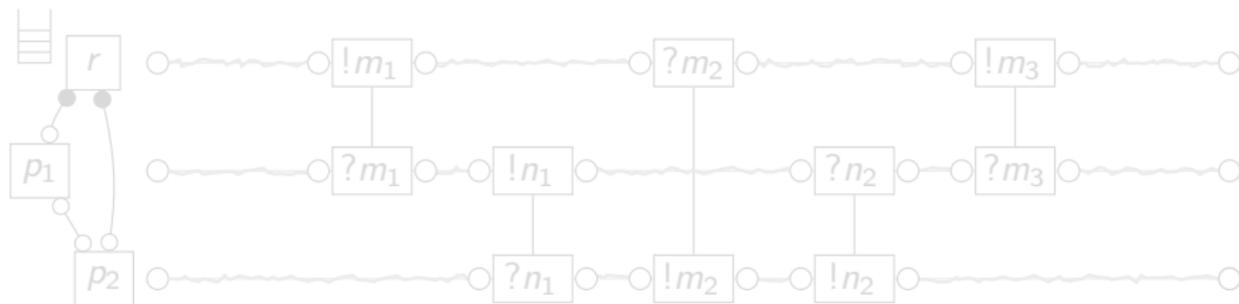
Theorem [Heußner et al. 2010]:

Reachability is decidable for RCPS iff they are well-queueing, eager, and imbalanced. (even ExpTime-complete!)

\Rightarrow original proof:

commutative **reordering** of interleaving allows 1-stack simulation

\Rightarrow reinterpret in partial-order/rungraph setting: **decomposition**



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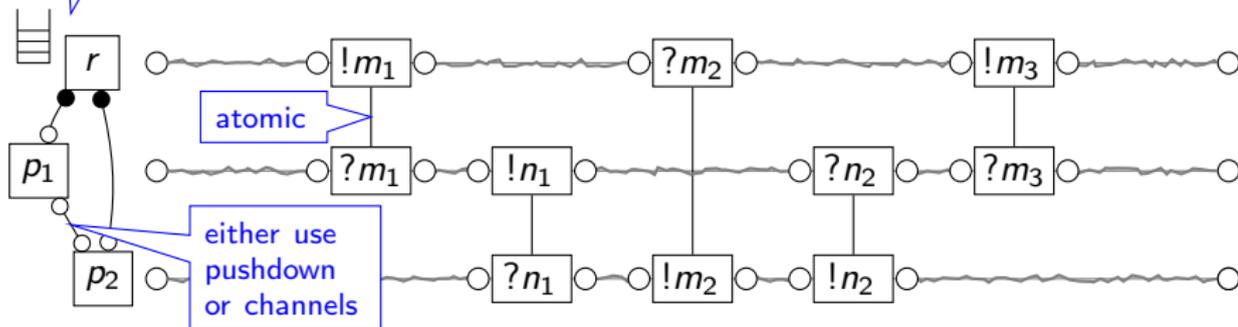
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use pushdown without restriction



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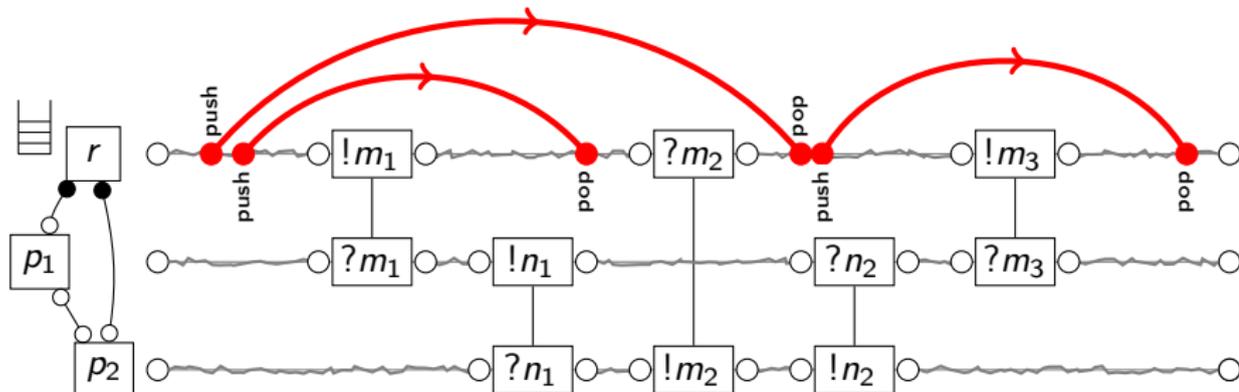
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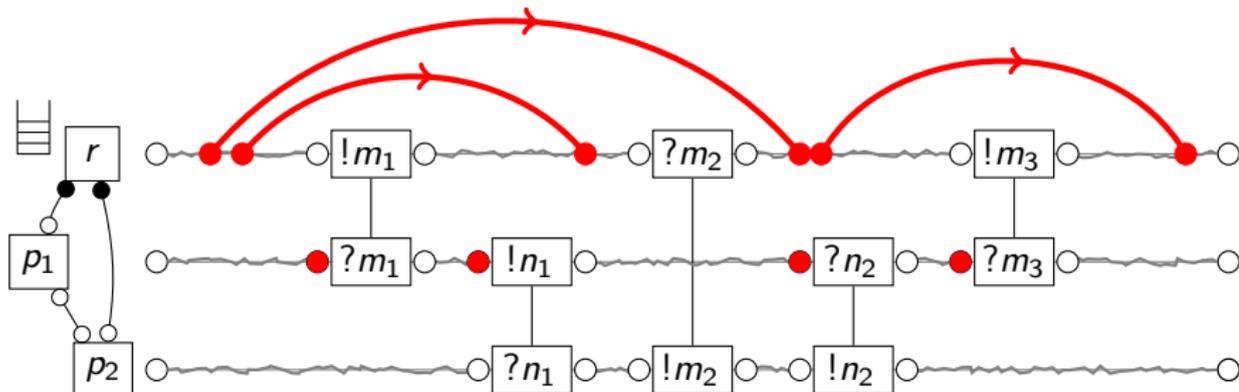
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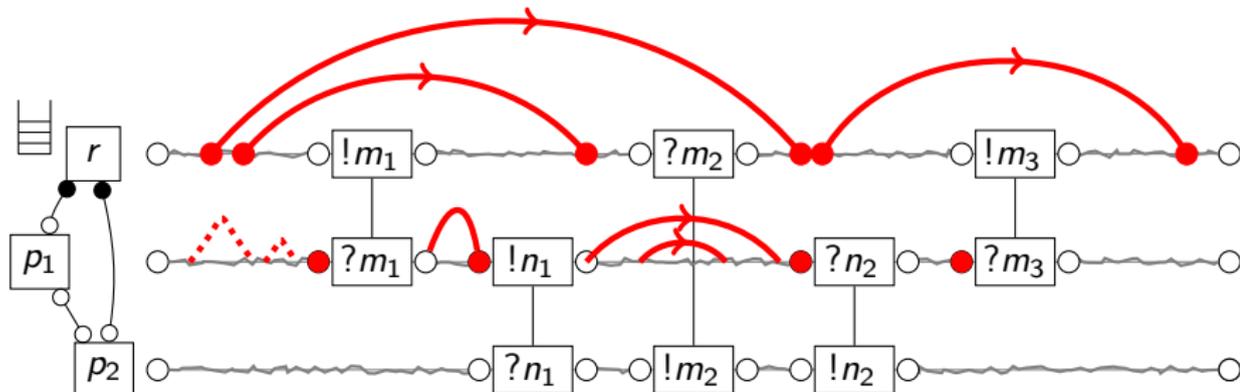
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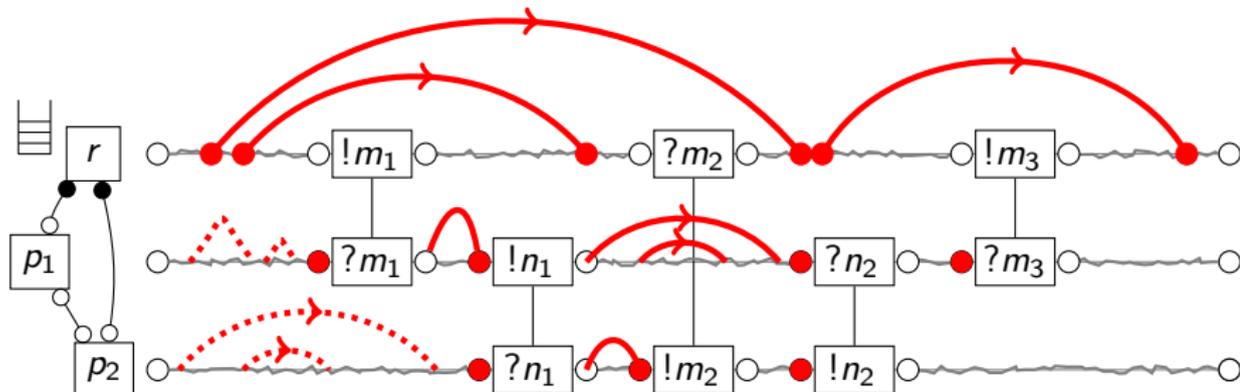
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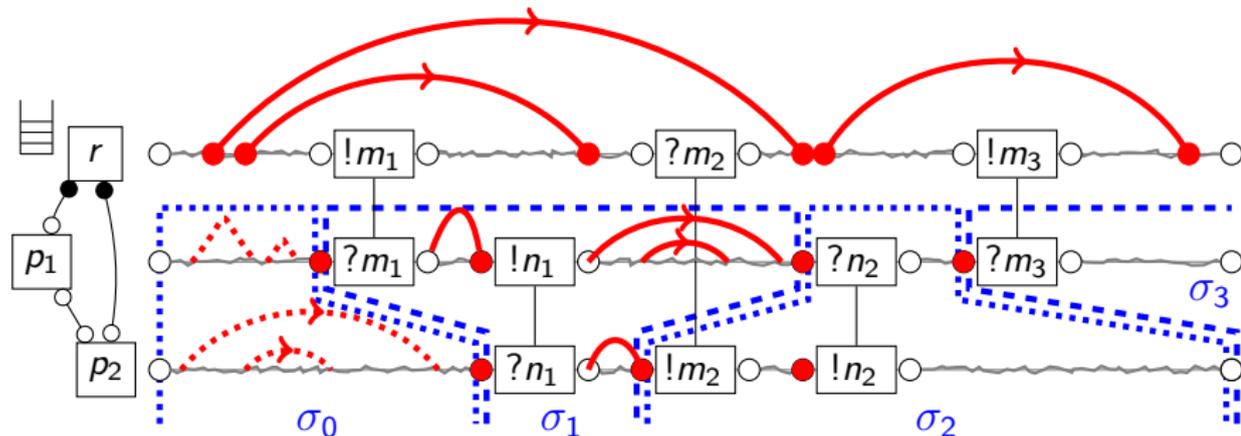
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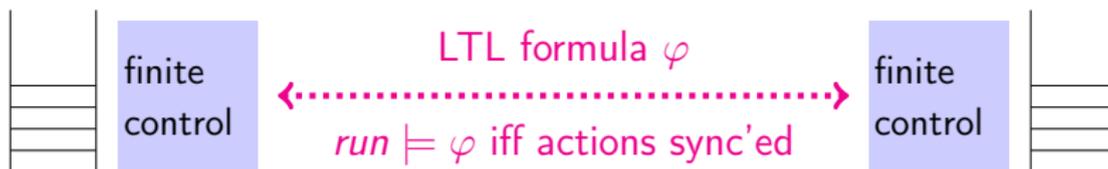
Bounded Ressources and LTL-MC

⇒ however extending this result leads directly to:

Theorem:

The LTL model checking question is undecidable for RQCPS that are well-queueing, eager and imbalanced. This already holds for a weak fragment of action LTL.

⇒ couple independent events by LTL interpreted on interleaving ⚡



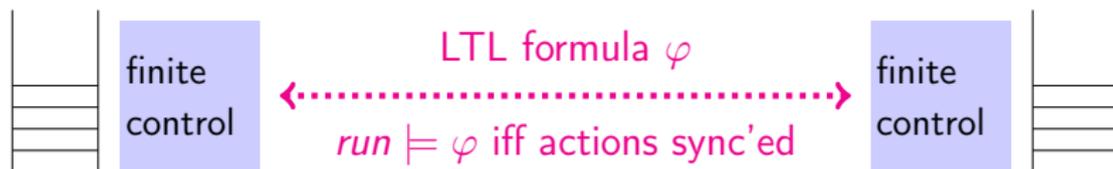
Bounded Ressources and LTL-MC

⇒ however extending this result leads directly to:

Theorem:

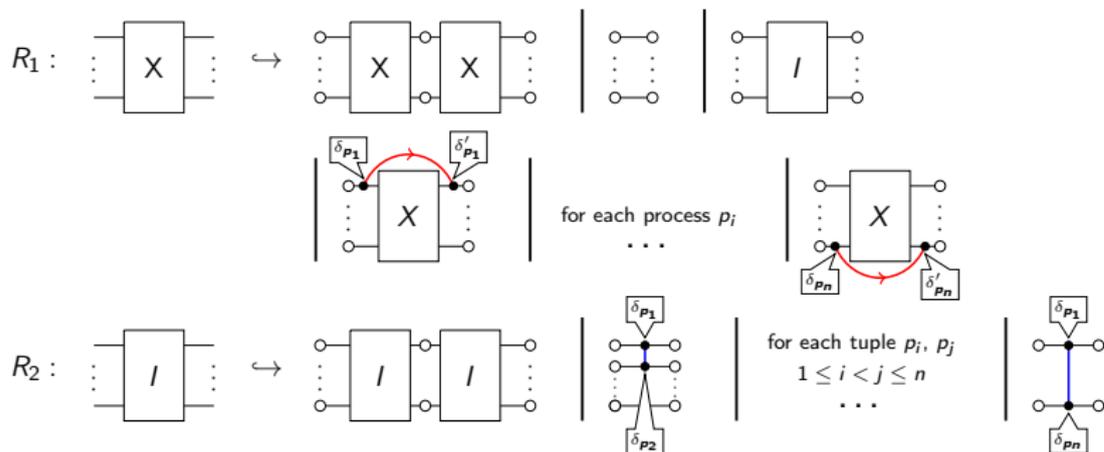
The LTL model checking question is undecidable for RQCPS that are well-queueing, eager and imbalanced. This already holds for a weak fragment of action LTL.

⇒ couple independent events by LTL interpreted on interleaving ⚡



⇒ leave interleaving semantics behind, look at rungraphs !

HRG for 1-stack reducible eager iRCPS



- **guess** “correct” labelling (transition rule $\delta \in \Delta_p$ f.e. process p)
- rulewidth bounded by $\mathcal{O}(\#\text{procs.})$
- correctness of labelling “local”: express by MSO formula φ_{label}
- model **check** in addition: $\varphi' \equiv \varphi \wedge \varphi_{\text{label}}$

MSO Model Checking RCPS

Theorem:

The MSO model checking question for rungraphs of RCPS that are eager, imbalanced and for which all runs can be reordered such that they are “1-stack reducible” is decidable.

- ⇒ cannot decide if for a given RCPS all runs can be reordered into a 1-stack one ⚡
- ⇒ but covers important practical examples 😊
(e.g., master-worker protocols etc.)
- ⇒ semantic boundedness versus syntactic description 😞

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Treewidth Boundedness

Conjecture:

Bounded treewidth of the underlying rungraphs is the most general form of semantic boundedness condition for which MSO model checking is decidable.

- ⇒ can generalize other boundedness conditions
(e.g., bounded phases for RCPS ✓ , lock graphs ✓ , etc.)
- ? how to derive algorithms that are usable in practice
- ? how to derive syntactic/decidable restrictions
- ? what about other graph boundedness measures
(cliquewidth, vertex cover, bounded pathwidth, ...)

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Related Works

- [Madhusudan et al.] LTL/MSO model checking for MSC-graphs
- [Parlato et al.'08] use tree-decomposition to derive new model checking algorithms (bounded phases. . .)
- MSO-definable temporal logics [Kuske/Gastin'10] and verification on partial orders of RCPS [Bollig et al.'11]
- partial-order versions of LTL (no consensus)
- novel boundedness conditions for asynchronous systems [LaTorre/Napoli'11] [Bouajjani/Emmi'12] etc.
- Autowrite tool [Durand/Courcelle]
- graph-rewriting based transition systems

Final Summary

- ⇒ leave behind interleaving semantics
- ⇒ focus rungraphs
- ⇒ describe generation of rungraphs by graph grammars
- ⇒ do model checking on rungraphs
- ⇒ known connection HRG-treewidth-MSO allows to derive decidability of model checking

